# ON THE OPERATOR EQUATION $A X-X B=C$ WITH UNBOUNDED OPERATORS $A, B$, AND $C$ 

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We find the criteria for the solvability of the operator equation $A X-X B=C$, where $A, B$, and $C$ are unbounded operators, and use the result to show existence and regularity of solutions of nonhomogeneous Cauchy problems.

## 1. Introduction

Let $A$ and $B$ be operators on Banach spaces $E$ and $F$, respectively, and let $C$ be an operator from $F$ to $E$. Of concern is the operator equation

$$
\begin{equation*}
A X-X B=C . \tag{1.1}
\end{equation*}
$$

To be found is a bounded operator $X$ from $F$ to $E$ such that $X(D(B) \cap D(C)) \subseteq$ $D(A)$ and $A X f-X B f=C f$ for every $f \in D(B) \cap D(C)$. Over the last few decades, (1.1) has been considered by many authors. It was first studied intensively for bounded operators by Daleckii and Krein [2], Rosenblum [16] (see also [5]). For unbounded operators $A$ and $B$, the case when $A$ and $B$ are generators of $C_{0}$-semigroups was considered in [1, 4, 10]. Recently, many papers apply the results to the stability and regularity of solutions of the abstract differential equation

$$
\begin{equation*}
u^{\prime}(t)=A u(t)+f(t), \tag{1.2}
\end{equation*}
$$

(see $[10,12,13]$ ), and the higher differential equation

$$
\begin{equation*}
u^{(n)}(t)=A u(t)+f(t) \tag{1.3}
\end{equation*}
$$

(see [8, 17]). On the other hand, it seems that there is little consideration of (1.1) when $C$ is an unbounded operator.

In this paper, we study (1.1) for this case. The motivation behind this is that, if $X$ is a bounded solution of (1.1), then the operator $\mathscr{A}^{\prime}:=\left(\begin{array}{cc}A & C \\ 0 & B\end{array}\right)$ is similar to the operator $\mathscr{A}:=\left(\begin{array}{cc}A & 0 \\ 0 & B\end{array}\right)$ by the identity

$$
\left(\begin{array}{ll}
A & C  \tag{1.4}\\
0 & B
\end{array}\right)=\left(\begin{array}{cc}
I & X \\
0 & I
\end{array}\right)\left(\begin{array}{cc}
A & 0 \\
0 & B
\end{array}\right)\left(\begin{array}{cc}
I & -X \\
0 & I
\end{array}\right)
$$

Therefore, many properties of $\mathscr{A}$ can be carried over to $\mathscr{A}^{\prime}$. Thus, instead of studying the unbounded perturbed operator $\mathscr{A}^{\prime}$ we just study the operator $\mathscr{A}$, which seems to be much simpler. In particular, the operator $\mathscr{A}^{\prime}$ is a generator of a $C_{0}$-semigroup on $E \times F$ if and only if $\mathscr{A}$ is a generator of a $C_{0}$-semigroup on $E \times F$. It is very useful, when converting the nonhomogeneous Cauchy problem

$$
\begin{equation*}
u^{\prime}(t)=A u(t)+f(t), \quad t \geq 0, \quad u(0)=x_{0} \in E \tag{1.5}
\end{equation*}
$$

where $f$ is a vector of a function space $F(\mathbb{R}, E)$, into a homogeneous problem

$$
U^{\prime}(t)=\left(\begin{array}{cc}
A & \delta_{0}  \tag{1.6}\\
0 & \frac{d}{d t}
\end{array}\right) ひ(t), \quad t \geq 0, \quad U(0)=\left(x_{0}, f\right) \text {. }
$$

on $E \times F(\mathbb{R}, E)$ (see $[6,7,9])$. Note that the operator $\delta_{0}$ is unbounded in some function space $F(\mathbb{R}, E)$.

We organize this paper as follows: in Section 2, we first show the solvability of (1.1). Then we give some applications to the existence and regularity of solutions of the nonhomogeneous Cauchy problem. In Section 3, we consider the nonhomogeneous differential equation

$$
\begin{equation*}
u^{\prime}(t)=A u(t)+f(t) \tag{1.7}
\end{equation*}
$$

on the line $\mathbb{R}$, where $f \in L^{p}(\mathbb{R}, E)$. It turns out that the existence and uniqueness of the bounded mild solution of (1.7) is equivalent to the solvability of equation $A X-X \mathscr{D}=\delta_{0}$. (See the notations below.)

We fix some notations. Let $E$ be a Banach space. The value of a functional $\phi \in E^{*}$ at a vector $x \in E$ is denoted by $\langle x, \phi\rangle$. By $W^{p, 1}(\mathbb{R}, E)$ we denote the space of all absolutely continuous functions $f$ from $\mathbb{R}$ to $E$ with $f^{\prime} \in L^{p}(\mathbb{R}, E)$. If $F(\mathbb{R}, E)$ is a certain function space over $E$, then $\mathscr{D}: D(\mathscr{D}) \subseteq F(\mathbb{R}, E) \rightarrow$ $F(\mathbb{R}, E)$ is defined by $\mathscr{D} f=f^{\prime}$ and $\delta_{0}: D\left(\delta_{0}\right) \subseteq F(\mathbb{R}, E) \rightarrow E$ by $\delta_{0}(f)=$ $f(0)$. Finally, for $\lambda \in \varrho(A),(\lambda-A)^{-1}$ is denoted by $R(\lambda, A)$.

## 2. Solution of the equation $A X-X B=C$

Throughout this paper, $A$ and $(-B)$ will denote generators of $C_{0}$-semigroups ( $T(t)$ ) and ( $S(t)$ ) on Banach spaces $E$ and $F$, respectively, and $C$ is an operator from $F$ to $E$. For the operator equation

$$
\begin{equation*}
A X-X B=C \tag{2.1}
\end{equation*}
$$

we recall a definition. Let $B$ be a linear operator on $F$. Then we say that $C: F \rightarrow E$ is $B$-bounded if $D(B) \subseteq D(C)$ and the operator $C(\lambda-B)^{-1}$ is bounded for one (all) $\lambda \in \varrho(B)$. For example, if $C$ is a closed operator with $D(B) \subseteq D(C)$, then $C$ is $B$-bounded. We have the following theorem about the solvability of (2.1).

Theorem 2.1. Let $A$ and $-B$ be generators of $C_{0}$-semigroups $(T(t))_{t \geq 0}$ and $(S(t))_{t \geq 0}$ on $E$ and $F$, respectively, and C B-bounded. Let

$$
\begin{align*}
& Q(t): F \supseteq D(B) \longmapsto E: Q(t) f:=T(t) C S(t) f, \quad t \geq 0 \\
& R(t): F \supseteq D(B) \longmapsto E: R(t) f:=-\int_{0}^{t} Q(s) f d s, \quad t \geq 0 \tag{2.2}
\end{align*}
$$

We assume that
(i) the weak-topology closure of $\{Q(t) f\}_{t \geq 0}$ contains 0 for every $f \in D(B)$;
(ii) $R(t)$ can be extended to a bounded operator for every $t \geq 0$ and the family $\{R(t)\}_{t \geq 0}$ is relatively compact in the weak operator topology.
Then (2.1) has a bounded solution.
Conversely, if (2.1) has a bounded solution, then $R(t)$ is bounded for every $t \geq 0$. In addition, if for every bounded operator $Y$ from $F$ to $E, T(t) Y S(t)$ converges to 0 as $t \rightarrow \infty$ in the weak (strong, uniform) operator topology, then the solution $X$ of (2.1) is unique, and $R(t)$ converges to $X$ in the weak (strong, uniform) operator topology.

Remark 2.2. The operator $R(t)$ is meaningful for each $t \geq 0$, since the function $t \rightarrow Q(t) f=T(t) C S(t) f=T(t) \cdot C R(\lambda, B) \cdot S(t) \cdot(\lambda-B) f$ is continuous for each $f \in D(B)$ and $\lambda \in \varrho(B)$.

Proof. Let $\lambda \in \varrho(B)$ and take $C_{1}=C R(\lambda, B)$. Then $C_{1}$ is bounded. For $t \geq 0$, we define the operators $Q_{1}(t): F \rightarrow E$ and $R_{1}(t): F \rightarrow E$ by

$$
\begin{align*}
Q_{1}(t) f & :=T(t) C_{1} S(t) f \\
R_{1}(t) f & :=-\int_{0}^{t} Q_{1}(s) f d s \tag{2.3}
\end{align*}
$$

Then $Q_{1}(t)$ and $R_{1}(t)$ are bounded operators. We now consider the operator equation

$$
\begin{equation*}
A Y-Y B=C_{1} \tag{2.4}
\end{equation*}
$$

By assumptions, there exists a net $t_{\alpha} \rightarrow \infty$ such that $T\left(t_{\alpha}\right) C S\left(t_{\alpha}\right)$ converges weakly to 0 and $R\left(t_{\alpha}\right)$ converges weakly to a bounded operator $Q$. Therefore, $T\left(t_{\alpha}\right) C_{1} S\left(t_{\alpha}\right)$ converges weakly to 0 and $R_{1}\left(t_{\alpha}\right)$ converges weakly to the bounded operator $Q R(\lambda, B)$. By [10, Theorem 3], (2.4) has a bounded solution, namely $Y=Q R(\lambda, B)$. It implies that $Y(\lambda-B)$ can be extended to the bounded operator $Q$. We verify that $Q=\overline{Y(\lambda-B)}$ is a solution of (2.1).

320 On the equation $A X-X B=C$
First, for any $f \in D\left(B^{2}\right)$ we have $(\lambda-B) f \in D(B)$ and

$$
\begin{align*}
A Q f-Q B f & =A Y(\lambda-B) f-Y(\lambda-B) B f \\
& =(A Y-Y B)(\lambda-B) f  \tag{2.5}\\
& =C_{1}(\lambda-B) f=C f
\end{align*}
$$

Hence, $A Q f-Q B f=C f$ and thus,

$$
\begin{equation*}
T(t) A Q S(t) f-T(t) Q S(t) B f=T(t) C S(t) f \tag{2.6}
\end{equation*}
$$

for all $f \in D\left(B^{2}\right)$. By [10, Lemma 1], if $f \in D\left(B^{2}\right)$ and $\phi \in D\left(A^{\prime}\right)$ we have

$$
\begin{align*}
\frac{d}{d t}\langle T(t) Q S(t) f, \phi\rangle & =\langle T(t) A Q S(t) f, \phi\rangle-\langle T(t) Q S(t) B f, \phi\rangle  \tag{2.7}\\
& =\langle T(t) C S(t) f, \phi\rangle
\end{align*}
$$

Therefore,

$$
\begin{align*}
\langle R(t) f, \phi\rangle & =-\int_{0}^{t}\langle T(s) C S(s) f, \phi\rangle d s \\
& =-\int_{0}^{t} \frac{d}{d s}\langle T(s) Q S(s) f, \phi\rangle d s  \tag{2.8}\\
& =-\langle T(t) X S(t) f-Q f, \phi\rangle
\end{align*}
$$

from which it follows that

$$
\begin{equation*}
R(t) f=Q f-T(t) Q S(t) f \tag{2.9}
\end{equation*}
$$

for $f \in D\left(B^{2}\right)$. Since the operators on both sides of (2.9) are bounded and $D\left(B^{2}\right)$ is dense in $F$, it implies that (2.9) also holds for all $f \in D(B)$.

Let now $f \in D(B)$ and $\phi \in D\left(A^{\prime}\right)$, then we have

$$
\begin{align*}
\langle T(t) C S(t) f, \phi\rangle & =\frac{d}{d t} \int_{0}^{t}\langle T(s) C S(s) f, \phi\rangle d s=-\frac{d}{d t}\langle R(t) f, \phi\rangle \\
& =\frac{d}{d t}\langle T(t) Q S(t) f-Q f, \phi\rangle=\frac{d}{d t}\langle T(t) Q S(t) f, \phi\rangle  \tag{2.10}\\
& =\langle T(s) A Q S(s) f-T(s) Q S(s) B f, \phi\rangle
\end{align*}
$$

which implies

$$
\begin{equation*}
T(t) A Q S(t) f-T(t) Q S(t) B f=T(t) C S(t) f \quad \forall t \geq 0 \tag{2.11}
\end{equation*}
$$

Taking $t=0$ we have $A Q f-Q B f=C f$ for $f \in D(B)$.
Conversely, if $X$ is a solution of (2.1), then by the same argument as above we have

$$
\begin{equation*}
R(t) f=X f-T(t) X S(t) f \tag{2.12}
\end{equation*}
$$

for $f \in D(B)$. Since all the operators on the right-hand side of (2.12) are bounded and $D(B)$ is dense in $F, R(t)$ can be extended to a bounded operator. Moreover, if $T(t) X S(t) \rightarrow 0$ in weak (resp., strong, uniform) operator topology, then $R(t) \rightarrow X$ weakly (resp., strongly, uniformly). Hence, $X$ is uniquely determined, and the proof is complete.

For a semigroup $(T(t))_{t \geq 0}$ generated by $A$, we define the growth bound $\omega(A)$ by

$$
\begin{equation*}
\omega(A):=\inf \left\{\lambda \in \mathbb{R}: \exists M>0 \text { such that }\|T(t)\| \leq M e^{\lambda t} \forall t \geq 0\right\} \tag{2.13}
\end{equation*}
$$

If $\omega(A)<0$, then $(T(t))$ is called uniformly exponentially stable. The following is a short version of Theorem 2.1, which gives the existence and uniqueness of the solution of (2.1) and will be used more frequently.

Theorem 2.3. Assume that $\omega(A)+\omega(-B)<0$ and that $R(t)$ is uniformly bounded. Then (2.1) has a unique bounded solution.

Proof. Since $A X-X B=(A+\lambda) X-X(B+\lambda)$, we can assume, without loss of generality, that $\omega(S)=0$ and $\omega(T)<0$. Then for any $\lambda \in \varrho(B)$ we have

$$
\begin{align*}
\|T(t) C S(t) f\| & =\|T(t) C R(\lambda, B) S(t)(\lambda-B) f\| \\
& \leq M_{1} e^{\omega(A) t} \cdot\|C R(\lambda, B)\| \cdot M_{2} \cdot\|(\lambda-B) f\| \longrightarrow 0 \tag{2.14}
\end{align*}
$$

So Theorem 2.1(i) is satisfied. In addition, for $t_{1}, t_{2} \rightarrow \infty$ and $f \in D(B)$ we have

$$
\begin{align*}
\left\|R\left(t_{1}\right) f-R\left(t_{2}\right) f\right\| & \leq \int_{t_{1}}^{t_{2}}\|T(s) C S(s) f\| d s \\
& \leq \int_{t_{1}}^{t_{2}} M_{1} e^{\omega(A) s}\|C R(\lambda, B)\| M_{2}\|(\lambda-B) f\| d s  \tag{2.15}\\
& \leq M \int_{t_{1}}^{t_{2}} e^{\omega(A) s} d s \longrightarrow 0 \quad \text { as } t_{1}, t_{2} \longrightarrow \infty
\end{align*}
$$

Since $R(t)$ is uniformly bounded and $D(B)$ is dense in $F, R(t)$ converges strongly to a bounded operator. So Theorem 2.1(ii) is satisfied. By Theorem 2.1, (1.1) has a solution, and since $\|T(t) Y S(t) f\| \rightarrow 0, t \rightarrow \infty$ for each bounded operator $Y: F \rightarrow E$, it is unique and equals to the bounded extension of $\lim _{t \rightarrow \infty} R(t)$.

The following corollary, which is involved with exponentially dichotomic semigroups follows directly from Theorem 2.3. Recall, a $C_{0}$-semigroup ( $T(t)$ ) on a Banach space $E$ is exponentially dichotomic, if there is a bounded projection $P$ on $E$ and positive constants, $M$ and $\omega$, such that
(i) $P T(t)=T(t) P$ for all $t \geq 0$;
(ii) $\|T(t) x\| \leq M e^{-\omega t}\|x\|$ for all $x \in P(E)$;
(iii) the restriction $\left.T(t)\right|_{\operatorname{ker}(P)}$ extends to a group and $\|T(-t) x\| \leq$ $M e^{-\omega t}\|x\|$ for all $x \in \operatorname{ker}(P)$ and $t \geq 0$.

It is well known that $(T(t))$ is exponentially dichotomic if and only if $\sigma(T(t)) \cap$ $\{\lambda \in \mathbb{C}:|\lambda|=1\}=\emptyset$ for all $t>0$ (cf. [14]). By the weak spectral mapping theorem, this implies that $\sigma(A) \cap i \mathbb{R}=\emptyset$. Also note that uniformly exponentially stable semigroup is a particular case of exponentially dichotomic one, when $P=I$, the identity operator.

Corollary 2.4. Let A be the generator of an exponentially dichotomic semigroup $(T(t))$ and $-B$ the generator of an isometric $C_{0}$-group. If $R(t)$ is uniformly bounded. Then (2.1) has a unique bounded solution.

Proof. Let $C_{1}=P C, C_{2}=(I-P) C, A_{1}=\left.A\right|_{P(E)}, A_{2}=\left.A\right|_{\operatorname{ker}(P)}$. It is easy to see that $C_{1}$ and $C_{2}$ are $B$-bounded. By Theorem 2.3, there is a unique bounded operator $X_{1}: F \rightarrow P(E)$ such that

$$
\begin{equation*}
A_{1} X_{1}-X_{1} B=C_{1} \tag{2.16}
\end{equation*}
$$

Moreover, $-A_{2}$ generates an exponentially stable semigroup and $B$ also generates an isometric group. Again, by Theorem 2.3, there is a unique bounded operator $X_{2}: F \rightarrow \operatorname{ker}(P)$ such that

$$
\begin{equation*}
-A_{2} X_{2}+X_{2} B=-C_{2}, \quad \text { or } \quad A_{2} X_{2}-X_{2} B=C_{2} . \tag{2.17}
\end{equation*}
$$

Let now $X=X_{1}+X_{2}$, then $A X-X B=A\left(X_{1}+X_{2}\right)-\left(X_{1}+X_{2}\right) B=\left(A_{1} X_{1}-\right.$ $\left.X_{1} B\right)+\left(A_{2} X_{2}-X_{2} B\right)=C_{1}+C_{2}=C$. Thus, $X$ is a bounded solution of (2.1). The uniqueness of $X$ follows from the fact that $P X$ and $(I-P) X$ are unique bounded solutions of (2.16) and (2.17), respectively.

In the following we apply the above results to study the existence and regularity of solutions of Cauchy problems.

Corollary 2.5. Let A be the generator of a $C_{0}$-semigroup $(T(t))$ on $E$ such that $\omega(T)<0$ and $\mathscr{D}: W^{p, 1}(\mathbb{R}, E) \rightarrow L^{p}(\mathbb{R}, E)$ be given by $\mathscr{D}=d / d t$. Then the equation

$$
\begin{equation*}
A X-X \mathscr{D}=\delta_{0} \tag{2.18}
\end{equation*}
$$

has a unique solution.
Proof. It is well known that $\delta_{0}$ is $\mathscr{D}$-bounded and $-\mathscr{D}$ is the generator of the shift $C_{0}$-group $S(t)$ given by $S(t) f(s)=f(s-t)$. Hence, $\omega(S)=0$. Moreover,

$$
\begin{align*}
\|R(t) f\| & =\left\|\int_{0}^{t} T(s) \delta_{0} S(s) f d s\right\|=\left\|\int_{0}^{t} T(s) f(-s) d s\right\|  \tag{2.19}\\
& \leq M \int_{0}^{t}\|f(-s)\| d s \leq M\|f\|
\end{align*}
$$

Hence $R(t), t \geq 0$, is uniformly bounded. Thus, by Theorem 2.3, (2.18) has a unique bounded solution.

From Corollary 2.5 we obtain the following.
Corollary 2.6. Let $p \geq 1$ and $A$ the generator of a $C_{0}$-semigroup in $E$. Then the operator

$$
\mathscr{A}:=\left(\begin{array}{cc}
A & \delta_{0}  \tag{2.20}\\
0 & \mathscr{D}
\end{array}\right)
$$

with $D(\mathscr{D}):=D(A) \times W^{1,1}(\mathbb{R}, E)$ is the generator of a $C_{0}$-semigroup on $E \times$ $L^{p}(\mathbb{R}, E)$.

Proof. Without loss of generality, we assume $\omega(T)<0$. Then, by Corollary 2.5, (2.18) has a unique solution. Hence, $\mathscr{A}$ is similar to the generator $\left(\begin{array}{cc}A & 0 \\ 0 & \mathscr{D}\end{array}\right)$ and thus is a generator.

It is well known (cf. [7]) that if $\left(u_{1}, u_{2}\right)^{T}$ is a (classical) solution of the Cauchy problem

$$
\begin{equation*}
U^{\prime}(t)=\mathscr{A} U(t) \quad t \geq 0, \quad \ddots(0)=\left(u_{0}, f\right)^{T} \tag{2.21}
\end{equation*}
$$

on $E \times F(\mathbb{R}, E)$, where $F(\mathbb{R}, E)$ is a function space, then the first component $u_{1}$ is the (classical) solution of the inhomogeneous Cauchy problem

$$
\begin{equation*}
u^{\prime}(t)=A u(t)+f(t) \quad t \geq 0, \quad u(0)=u_{0} \tag{2.22}
\end{equation*}
$$

From the above observation and Corollary 2.6 we obtain the following.
Corollary 2.7. Let $A$ be the generator of a $C_{0}$-semigroup and $f \in W^{1,1}(\mathbb{R}, E)$, then (2.22) has a unique classical solution.

Now recall the definition of extrapolation space. Let $A$ be the generator of a $C_{0}$-semigroup ( $T(t)$ ) on a Banach space $E$ and $\lambda \in \varrho(A)$. On $E$ we introduce a new norm by

$$
\begin{equation*}
\|x\|_{-1}=\|R(\lambda, A) x\| \tag{2.23}
\end{equation*}
$$

Then the completion of $\left(E, \|_{-\|_{-1}}\right)$ is called the extrapolation space of $E$ associated with $A$, and is denoted by $E_{-1}$. It is shown that the operator $T(t)$ can
be uniquely extended to a bounded operator on the Banach space $E_{-1}$. The result is a $C_{0}$-semigroup on $E_{-1}$, denoted by $\left(T_{-1}(t)\right)$. The semigroup $\left(T_{-1}(t)\right)$ is called the extrapolated semigroup of $(T(t))$. If we denote by $A_{-1}$ the generator of $\left(T_{-1}(t)\right)$ on $E_{-1}$, then we have the following properties (see more details in [3, 7]):
(i) $\left\|T_{-1}(t)\right\|_{L\left(E_{-1}\right)}=\|T(t)\|_{L(E)}$;
(ii) $E$ is dense in $E_{-1}$ and $D\left(A_{-1}\right)=E$;
(iii) $A_{-1}: E \rightarrow E_{-1}$ is the unique extension of $A: D(A) \rightarrow E$ to $E \rightarrow E_{-1}$.

The following two corollaries show the existence and uniqueness of the classical solution of the nonhomogeneous Cauchy problem (2.22) for the case that the nonhomogeneous term $f$ is not differentiable. Since their proofs are similar, we present here only one of them.

Corollary 2.8. Let $A$ be the generator of an analytic semigroup. Then (2.22) has a unique classical solution for every $x \in D(A)$ and Hölder continuous function $f \in H_{\alpha}(\mathbb{R}, E)$.

Corollary 2.9. Let $A$ be the generator of a $C_{0}$-semigroup on $E$. Then (2.22) has a unique classical solution for every $x \in D(A)$ and $f \in B U C(\mathbb{R},[D(A)])$, where $[D(A)]$ is the Banach space $\left(D(A),\|\cdot\|_{A}\right)$ with the norm $\|x\|_{A}=\|x\|+$ $\|A x\|$.

Proof of Corollary 2.9. Without loss of generality, we assume $\omega(A)<0$. In view of the previous observation we have only to show that $\mathscr{A}:=\left(\begin{array}{cc}A & \delta_{0} \\ 0 & \mathscr{D}\end{array}\right)$ with $D(A)=D(A) \times B U C(\mathbb{R},[D(A)])$ is a generator of a $C_{0}$-semigroup on $E \times$ $B U C_{-1}(\mathbb{R},[D(A)])$, where $B U C_{-1}(\mathbb{R},[D(A)])$ is the extrapolated space of $B U C(\mathbb{R},[D(A)])$ associated with $\mathscr{D}=d / d t$ on $B U C(\mathbb{R},[D(A)])$. This is done if we show that there is a bounded solution of the operator equation

$$
\begin{equation*}
A X-X \mathscr{D}=\delta_{0}, \tag{2.24}
\end{equation*}
$$

where $F:=B U C_{-1}(\mathbb{R},[D(A)])$. It is easy to see that $\delta_{0}$ is $\mathscr{D}$-bounded. Since $\omega(\mathscr{D})=0$ we have $\omega(A)+\omega(\mathscr{D})<0$. Moreover, let $f \in B U C(\mathbb{R},[D(A)])$ and $g(t)=R(1, \mathscr{D}) f(t)$, then we have

$$
\begin{aligned}
\|R(t) f\| & =\left\|\int_{0}^{t} T(s) f(-s) d s\right\|=\left\|\int_{0}^{t} T(s)\left(g(-s)-g^{\prime}(-s)\right) d s\right\| \\
& \leq\left\|\int_{0}^{t} T(s) g(-s) d s\right\|+\left\|\int_{0}^{t} T(s) g^{\prime}(-s) d s\right\| \\
& \leq\left\|\int_{0}^{t} T(s) g(-s) d s\right\|+\left\|\int_{0}^{t} T(s) A g(-s) d s\right\|
\end{aligned}
$$

$$
\begin{align*}
& +\|T(t) g(-t)\|+\|g(0)\| \\
\leq & C\left(\sup _{s \in \mathbb{R}}\|g(s)\|+\sup _{s \in \mathbb{R}}\|A g(s)\|\right) \\
= & C\|g\|_{B U C(\mathbb{R},[D(A)])}=C\|R(1, \mathscr{D}) f\|_{B U C(\mathbb{R},[D(A)])} \\
= & C\|f\|_{B U C_{-1}(\mathbb{R},[D(A)])} \tag{2.25}
\end{align*}
$$

Here we used the fact that $\int_{0}^{t} T(s) g^{\prime}(-s) d s=\int_{0}^{t} A T(s) g(-s) d s-T(t) g(-t)+$ $g(0)$. Since $B U C(\mathbb{R},[D(A)])$ is dense in $B U C_{-1}(\mathbb{R},[D(A)]), R(t)$ is uniformly bounded. By Theorem 2.3, (2.24) has a unique bounded solution, and this concludes the proof.

We complete this section with the following result, which is very helpful for studying properties of unbounded perturbed generators.

THEOREM 2.10. For the operator matrix $\mathscr{A}=\left(\begin{array}{cc}A & C \\ 0 & B\end{array}\right)$ with $D(\mathscr{A})=D(A) \times D(B)$ assume that $A$ is the generator of a $C_{0}$-semigroup on $E, B$ is the generator of a bounded $C_{0}$-group on $F$ and $C$ is $B$-bounded. Then $\mathscr{A}$ is a generator of a $C_{0}$-semigroup on $E \times F$ if and only if $\mathscr{A}$ is of the form

$$
\mathscr{A}=2\left(\begin{array}{ll}
A & 0  \tag{2.26}\\
0 & B
\end{array}\right) 2^{-1}+\mathscr{L}
$$

with an isomorphism 2 and a bounded operator $\mathscr{L}$ in $E \times F$.
Proof. We have only to show the "only if" part. By the assumption we have $\omega(S)=0$, where $(S(t))_{t \in \mathbb{R}}$ is the group of $-B$. Without loss of generality, we assume $\omega(T)<0$. Since $\mathscr{A}$ is the generator of a $C_{0}$-semigroup on $E \times F$, by [6, Theorem 3.1], we have

$$
\begin{equation*}
V(t):=\int_{0}^{t} T(t-s) C S(-s) d s=\int_{0}^{t} T(s) C S(s-t) d s \tag{2.27}
\end{equation*}
$$

is bounded for $t \geq 0$. Thus,

$$
\begin{align*}
\|R(t) f\| & =\left\|\int_{0}^{t} T(s) C S(s) f d s\right\|=\left\|\int_{0}^{t} T(s) C S(s-t) S(t) f d s\right\|  \tag{2.28}\\
& \leq\|V(t)\| \cdot\|S(t) f\| \leq\|V(t)\| \cdot\|S(t)\| \cdot\|f\|
\end{align*}
$$

Hence $R(t)$ is bounded for every $t \geq 0$. By Corollary 2.3, the equation $A X-$ $X B=C$ has a unique bounded solution $X$. Therefore,

$$
\mathscr{A}=\left(\begin{array}{cc}
I & -X  \tag{2.29}\\
0 & I
\end{array}\right)\left(\begin{array}{cc}
A & 0 \\
0 & B
\end{array}\right)\left(\begin{array}{cc}
I & X \\
0 & I
\end{array}\right)
$$

and the corollary is proved.

326 On the equation $A X-X B=C$

## 3. Regularity of solutions of differential equations

In this section, we consider the differential equation on the line $\mathbb{R}$

$$
\begin{equation*}
u^{\prime}(t)=A u(t)+f(t), \quad t \in \mathbb{R} \tag{3.1}
\end{equation*}
$$

where $A$ is the generator of a $C_{0}$-semigroup $(T(t))_{t \geq 0}$ on $E$ and $f \in L^{p}(\mathbb{R}, E)$. We say that the continuous function $u(t)$ is a mild solution of (3.1), if

$$
\begin{equation*}
u(t)=T(t-s) u(s)+\int_{s}^{t} T(t-\tau) f(\tau) d \tau \tag{3.2}
\end{equation*}
$$

for all $t \geq s$. It turns out that the existence and uniqueness of bounded mild solutions of (3.1) is closely related to the solvability of operator equations, as the following theorem shows.

Theorem 3.1. Let A be a generator of a $C_{0}$-semigroup $(T(t))_{t \geq 0}$ with $\sigma(A) \cap$ $i \mathbb{R}=\emptyset$. Then the following are equivalent:
(a) For each function $f$ in $L^{p}(\mathbb{R}, E)$ there exists a unique mild solution of (3.1), which is bounded.
(b) There exists a unique bounded solution of the operator equation

$$
\begin{equation*}
A X-X \mathscr{D}=-\delta_{0}, \tag{3.3}
\end{equation*}
$$

where $F=L^{p}(\mathbb{R}, E), \mathscr{D}: W^{p, 1}(\mathbb{R}, E) \rightarrow F$, and $\delta_{0}: W^{p, 1}(\mathbb{R}, E) \rightarrow E$.
Proof. (i) $\Rightarrow$ (ii). Let $C(\mathbb{R}, E)$ be the space of all bounded continuous functions over $E$ and $G: L^{p}(\mathbb{R}, E) \rightarrow C(\mathbb{R}, E)$ the operator defined by $G f=u$ where $u$ is the unique mild solution of (3.1) corresponding to $f$. By standard argument, it is easy to see that $G$ is a closed, and hence, a bounded operator. Define $X f=(G f)(0)$. Then $X$ is a bounded operator from $L^{p}(\mathbb{R}, E)$ to $E$.

Let now $f \in W^{p, 1}(\mathbb{R}, E)$. By Corollary $2.7, u=G f$ is a classical solution of (3.1), that is,

$$
\begin{equation*}
(G f)^{\prime}(t)=A(G f)(t)+f(t) \tag{3.4}
\end{equation*}
$$

Note that, $(G f)^{\prime}=G\left(f^{\prime}\right)$. Hence $\left(G f^{\prime}\right)(t)=A(G f)(t)+f(t)$. Taking $t=0$, we have $A X f-X \mathscr{D} f=-\delta_{0} f$ for $f \in \mathscr{D}$, that is, $X$ is a bounded solution of (3.3).

To show the uniqueness, we assume that $X_{0}$ is a solution of equation $A X-$ $X \mathscr{D}=0$. Then for every $f \in \mathscr{D}$ the function $u \in \mathcal{M}$ defined by $u(t)=X S(t) f$ is a classical solution of (3.1), since

$$
\begin{equation*}
u^{\prime}(t)=X \mathscr{D} S(t) f=\left(A X+\delta_{0}\right) S(t) f=A u(t)+f(t) \tag{3.5}
\end{equation*}
$$

for all $t \in \mathbb{R}$. Let now $f \in \mathcal{M}$ and $\left(f_{k}\right)_{k \in \mathbb{N}} \subseteq D(\mathscr{D})$ with $\lim _{k} f_{k}=f$. Then $\lim _{k} u_{k}=\lim _{k} X S(\cdot) f_{k}=X S(\cdot) f$. Hence, taking the limit on both sides of
$u_{k}=G f_{k}$ as $k \rightarrow \infty$ we get $X S(\cdot) f=G f$, that is, $u=X S(\cdot) f$ is a mild solution of (3.1). Assume now that $X_{1}$ and $X_{2}$ are two solutions of (3.3). Then, for every $f \in \mathcal{M}, u=\left(X_{1}-X_{2}\right) S(\cdot) f$ is a mild solution (3.1). By the uniqueness of the mild solution we have $u \equiv 0$, which implies $X_{1}=X_{2}$.
(ii) $\Rightarrow$ (i). We have shown above that, if $X$ is a bounded solution of (3.3), then $u(t):=X S(t) f$ is a mild solution of (3.1). It remains to be shown that this solution is unique. In order to do this, assume that $v$ is a mild solution of the homogeneous equation $u^{\prime}(t)=A u(t), t \in \mathbb{R}$. It is the well-known Tauberian theorem (cf. [11]) that the spectrum of the function $f, \operatorname{sp}(f)$, satisfies $i \operatorname{sp}(v) \subseteq$ $\sigma(A)$. By assumption, $\sigma(A) \cap i \mathbb{R}=\emptyset$, so that $\operatorname{sp}(v)=\emptyset$, and so $v \equiv 0$ (see [15, page 22]), and the theorem is proved.

From Corollary 2.5 and Theorem 3.1 we obtain the following corollary.
Corollary 3.2. If $A$ is the generator of an exponentially dichotomic $C_{0}$ semigroup, then for every function $f$ if $L^{p}(\mathbb{R}, E)$, (3.1) has a unique bounded mild solution.

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